

**Computational Geometry**

<b>Semester IV</b>	<b>Subject Code: BS41603</b>	<b>Lectures: 60</b>
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**Objectives:**

The syllabus aims in equipping students with,

- Understanding mathematical base of computer graphics and animation
- Solid foundation in the field and to study some applications of Computational Geometry

**Unit 1: Two dimensional transformations**

16

- Representation of points
- Transformations and matrices
- Transformation of points
- Transformation of straight lines
- Midpoint transformation
- Transformation of parallel lines
- Transformation of intersecting lines
- Transformation , rotations, reflections, scaling, shearing
- Combined transformations
- Transformation of a unit square
- Solid body transformations
- Transformation and homogeneous coordinates, Translation
- Rotation about an arbitrary point
- Reflection through an arbitrary line
  - Projection – a geometric interpretation of homogeneous coordinates
  - Overall Scaling
- Point at infinity



<b>Unit 2: Three dimensional transformations</b>	16
<ul style="list-style-type: none"> <li>• Introduction</li> <li>• Three dimensional –Scaling, shearing, rotation, reflection, translation</li> <li>• Multiple transformations</li> <li>• Rotation about – an axis parallel to coordinates axes, an arbitrary axis in space</li> <li>• Reflection through – coordinates planes, planes parallel to coordinate planes, arbitrary planes</li> <li>• Affine and perspective transformations</li> <li>• Orthographic projections</li> <li>• Axonometric projections</li> <li>• Oblique projections</li> <li>• Single point perspective transformations</li> <li>• Vanishing points</li> </ul>	

<b>Unit 3: Plane Curves</b>	10
<ul style="list-style-type: none"> <li>• Introduction</li> <li>• Curve representation</li> <li>• Non – parametric curves</li> <li>• Parametric curves</li> <li>• Parametric representation of a circle and generation of circle</li> <li>• Parametric representation of an ellipse and generation of ellipse</li> <li>• Parametric representation of a parabola and generation of parabolic Segment</li> <li>• Parametric representation of a hyperbola and generation of hyperbolic segment.</li> </ul>	





<b>Unit 4: Space curve</b>	<b>6</b>
<ul style="list-style-type: none"><li>• Bezier Curves – Introduction, definition, properties (without proof)</li><li>• Curve fitting (upto <math>n = 3</math>) equation of the curve in matrix form ( upto <math>n = 3</math>)</li><li>• B Spline Curve-Introduction, definition and properties(without proof)</li></ul>	

\*Contact hours – 12 hours

**Reference Books:**

1. D. F. Rogers, J. A. Adams, *Mathematical elements for Computer graphics*, Sec ond edition, Mc Graw Hill Intel Edition.
2. Schaum Series, *Computer Graphics*.
3. Donald Hearn, M. Pauline Baker, *Computer Graphics C Version*, Second edition, Pearson

